Dynamics on character varieties

Bill Goldman University of Maryland

5 April 2024 Maryland Dynamics Conference celebrating Giovanni Forni's 60th birthday

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ 三 のへぐ

Dynamics on character varieties and geometric structures

Abstract

Classifying geometric structures on manifolds naturally leads to actions of mapping class groups on character varieties. For example complete affine structures on closed surfaces are classified by GL(2, \mathbb{Z})-orbits on \mathbb{R}^2 . Particularly basic are the automorphisms of the variant of the Markoff surface $x^2 + y^2 + z^2 - xyz = 20$ where the dynamics bifurcates between ergodic (level < 20) and not ergodic (level > 20).



References

- W. Goldman, "Geometric Structures on Manifolds", Graduate Studies in Math. 227, American Mathematical Society (2023).
- A. Sikora, "Character Varieties," Trans. A.M.S. 364 (2012), no.10, 5173–5208, arXiv:0902.2589v3
- W. Goldman, "Trace coordinates on Fricke spaces of some simple hyperbolic surfaces," Chapter 15, pp. 611–684, of Handbook of Teichmüller theory, vol. II (A. Papadopoulos, ed.), IRMA Lectures in Mathematics and Theoretical Physics volume 13, European Mathematical Society (2008), math.GM.0402103
- W. Goldman, Action of the modular group on real SL(2)-characters of a one-holed torus," Geometry and Topology 7 (2003), 443–486. mathDG/0305096.

▲□▶▲圖▶▲≣▶▲≣▶ ≣ のQ@

Lie and Klein (1872): A geometry consists of the properties of a space X invariant under transitive action of a Lie group G.

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ 三 のへぐ

Lie and Klein (1872): A geometry consists of the properties of a space X invariant under transitive action of a Lie group G.

• Ehresmann (1936): Manifolds locally modeled on (G, X).

Lie and Klein (1872): A geometry consists of the properties of a space X invariant under transitive action of a Lie group G.

- Ehresmann (1936): Manifolds locally modeled on (G, X).
- Examples include:

Lie and Klein (1872): A geometry consists of the properties of a space X invariant under transitive action of a Lie group G.

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

- Ehresmann (1936): Manifolds locally modeled on (G, X).
- Examples include:

Euclidean structures (flat Riemanian metrics);

Lie and Klein (1872): A geometry consists of the properties of a space X invariant under transitive action of a Lie group G.

- ▶ Ehresmann (1936): Manifolds locally modeled on (*G*, *X*).
- Examples include:
 - Euclidean structures (flat Riemanian metrics);
 - ▶ Hyperbolic structures (metrics of curvature −1);

- Lie and Klein (1872): A geometry consists of the properties of a space X invariant under transitive action of a Lie group G.
- ▶ Ehresmann (1936): Manifolds locally modeled on (*G*, *X*).
- Examples include:
 - Euclidean structures (flat Riemanian metrics);
 - ▶ Hyperbolic structures (metrics of curvature −1);
 - Affine structures (flat affine connections of zero torsion).

- Lie and Klein (1872): A geometry consists of the properties of a space X invariant under transitive action of a Lie group G.
- ▶ Ehresmann (1936): Manifolds locally modeled on (*G*, *X*).
- Examples include:
 - Euclidean structures (flat Riemanian metrics);
 - ▶ Hyperbolic structures (metrics of curvature −1);
 - Affine structures (flat affine connections of zero torsion).
- Can introduce isolated singularities with specified cone angles

 for example, translation surfaces are very special singular
 Euclidean structures.

・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・

▲ロト ▲圖 ▶ ▲ 国 ▶ ▲ 国 ▶ ● 回 ● の Q @

Classifying such (G, X)-structures on a fixed topology Σ leads to action of the mapping class group

$$\mathsf{Mod}(\Sigma) := \pi_0 \big(\mathsf{Diff}(\Sigma)\big) \longrightarrow \mathsf{Out}(\pi)$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

on deformation space $\text{Def}_{(G,X)}(\Sigma)$ of marked (G, X)-structures.

Classifying such (G, X)-structures on a fixed topology Σ leads to action of the mapping class group

$$\mathsf{Mod}(\Sigma) := \pi_0 \big(\mathsf{Diff}(\Sigma)\big) \longrightarrow \mathsf{Out}(\pi)$$

・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・

on deformation space $Def_{(G,X)}(\Sigma)$ of marked (G, X)-structures.

• $Def_{(G,X)}(\Sigma)$ itself locally modeled on $Rep(\pi, G)$

Classifying such (G, X)-structures on a fixed topology Σ leads to action of the mapping class group

$$\mathsf{Mod}(\Sigma) := \pi_0 \big(\mathsf{Diff}(\Sigma)\big) \longrightarrow \mathsf{Out}(\pi)$$

on deformation space $\text{Def}_{(G,X)}(\Sigma)$ of marked (G,X)-structures.

- $Def_{(G,X)}(\Sigma)$ itself locally modeled on $Rep(\pi, G)$
- Mod(Σ)-action on Def_(G,X)(Σ) corresponds to Out(π)-action on Rep(π, G).

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ 三三 - のへぐ

Euclidean geometry occurs where $X = \mathbb{R}^n$ and G = Isom(X). Let Σ be the *n*-torus.

Euclidean geometry occurs where $X = \mathbb{R}^n$ and G = Isom(X). Let Σ be the *n*-torus.

• A *Euclidean structure* on Σ (a flat Riemannian metric) identifies Σ with a flat torus \mathbb{R}^n / Λ where $\Lambda < \mathbb{R}^n$ is a lattice.

Euclidean geometry occurs where $X = \mathbb{R}^n$ and G = Isom(X). Let Σ be the *n*-torus.

A Euclidean structure on Σ (a flat Riemannian metric) identifies Σ with a flat torus ℝⁿ/Λ where Λ < ℝⁿ is a lattice.

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

• A marking of Σ is just a basis of Λ .

Euclidean geometry occurs where $X = \mathbb{R}^n$ and G = Isom(X). Let Σ be the *n*-torus.

- A Euclidean structure on Σ (a flat Riemannian metric) identifies Σ with a flat torus ℝⁿ/Λ where Λ < ℝⁿ is a lattice.
- A marking of Σ is just a basis of Λ .
- ▶ The space of marked lattices (bases of \mathbb{R}^n) is just $GL(n, \mathbb{R})$.

Euclidean geometry occurs where $X = \mathbb{R}^n$ and G = Isom(X). Let Σ be the *n*-torus.

- A Euclidean structure on Σ (a flat Riemannian metric) identifies Σ with a flat torus ℝⁿ/Λ where Λ < ℝⁿ is a lattice.
- A marking of Σ is just a basis of Λ .
- ▶ The space of marked lattices (bases of \mathbb{R}^n) is just $GL(n, \mathbb{R})$.
- Thus the deformation space Def_(G,X)(Σ) of isometry classes of marked flat tori is just the space GL(n, R)/O(n).

Euclidean geometry occurs where $X = \mathbb{R}^n$ and G = Isom(X). Let Σ be the *n*-torus.

- A Euclidean structure on Σ (a flat Riemannian metric) identifies Σ with a flat torus ℝⁿ/Λ where Λ < ℝⁿ is a lattice.
- A marking of Σ is just a basis of Λ .
- ▶ The space of marked lattices (bases of \mathbb{R}^n) is just $GL(n, \mathbb{R})$.
- Thus the deformation space Def_(G,X)(Σ) of isometry classes of marked flat tori is just the space GL(n, R)/O(n).

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

• The mapping class group $Mod(\Sigma) = GL(n, \mathbb{Z})$.

Euclidean geometry occurs where $X = \mathbb{R}^n$ and G = Isom(X). Let Σ be the *n*-torus.

- A Euclidean structure on Σ (a flat Riemannian metric) identifies Σ with a flat torus ℝⁿ/Λ where Λ < ℝⁿ is a lattice.
- A marking of Σ is just a basis of Λ .
- ▶ The space of marked lattices (bases of \mathbb{R}^n) is just $GL(n, \mathbb{R})$.
- Thus the deformation space Def_(G,X)(Σ) of isometry classes of marked flat tori is just the space GL(n, R)/O(n).
- The mapping class group $Mod(\Sigma) = GL(n, \mathbb{Z})$.
- The moduli space of flat n-tori is the biquotient

 $GL(n,\mathbb{Z})\backslash GL(n,\mathbb{R})/O(n)$

・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・

▲□▶▲圖▶★≣▶★≣▶ ≣ の�?

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ 三 のへぐ

The Riemann moduli space M(Σ) parametrizes Riemann surfaces M of a fixed topology Σ.

- The Riemann moduli space M(Σ) parametrizes Riemann surfaces M of a fixed topology Σ.
 - Quasiprojective variety over C; singular exactly at Riemann surfaces with *nontrivial* automorphisms.

- The Riemann moduli space M(Σ) parametrizes Riemann surfaces M of a fixed topology Σ.
 - Quasiprojective variety over C; singular exactly at Riemann surfaces with *nontrivial* automorphisms.

More tractable object:

Teichmüller space $\mathfrak{T}(\Sigma)$ of marked Riemann surfaces (M, f): metric space/complex manifold $\approx \mathbb{R}^{6g-6}$.

- The Riemann moduli space M(Σ) parametrizes Riemann surfaces M of a fixed topology Σ.
 - Quasiprojective variety over C; singular exactly at Riemann surfaces with *nontrivial* automorphisms.

More tractable object:

Teichmüller space $\mathfrak{T}(\Sigma)$ of marked Riemann surfaces (M, f): metric space/complex manifold $\approx \mathbb{R}^{6g-6}$.

・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・

Marking: Diffeomorphism Σ → M;
 Riemann surface M varies, but the topology Σ fixed.

- The Riemann moduli space M(Σ) parametrizes Riemann surfaces M of a fixed topology Σ.
 - Quasiprojective variety over C; singular exactly at Riemann surfaces with *nontrivial* automorphisms.

More tractable object:

Teichmüller space $\mathfrak{T}(\Sigma)$ of marked Riemann surfaces (M, f): metric space/complex manifold $\approx \mathbb{R}^{6g-6}$.

・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・

- Marking: Diffeomorphism Σ → M; Riemann surface M varies, but the topology Σ fixed.
- Equivalence classes \longleftrightarrow Mod (Σ) -orbits on $\mathfrak{T}(\Sigma)$.

- The Riemann moduli space M(Σ) parametrizes Riemann surfaces M of a fixed topology Σ.
 - Quasiprojective variety over C; singular exactly at Riemann surfaces with *nontrivial* automorphisms.

More tractable object:

Teichmüller space $\mathfrak{T}(\Sigma)$ of marked Riemann surfaces (M, f): metric space/complex manifold $\approx \mathbb{R}^{6g-6}$.

・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・

- Marking: Diffeomorphism $\Sigma \xrightarrow{f} M$; Riemann surface M varies, but the topology Σ fixed.
- Equivalence classes \longleftrightarrow Mod (Σ) -orbits on $\mathfrak{T}(\Sigma)$.

$$\blacktriangleright \mathfrak{M}(\Sigma) = \mathfrak{T}(\Sigma)/\mathsf{Mod}(\Sigma).$$

◆□▶ ◆□▶ ◆ 臣▶ ◆ 臣▶ ○ 臣 ○ の Q @

• Geometry: Homogeneous space X = G/H.

- Geometry: Homogeneous space X = G/H.
- Topology: Manifold Σ with universal covering $\widetilde{\Sigma} \longrightarrow \Sigma$ and fundamental group π .

- Geometry: Homogeneous space X = G/H.
- Topology: Manifold Σ with universal covering $\widetilde{\Sigma} \longrightarrow \Sigma$ and fundamental group π .

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

• *Marking:* Diffeomorphism $\Sigma \xrightarrow{f} M$; the geometry on M varies, but the topology of Σ remains fixed.

- Geometry: Homogeneous space X = G/H.
- Topology: Manifold Σ with universal covering $\widetilde{\Sigma} \longrightarrow \Sigma$ and fundamental group π .
- *Marking:* Diffeomorphism $\Sigma \xrightarrow{f} M$; the geometry on M varies, but the topology of Σ remains fixed.
 - Patches U ⊂ M: Coordinate atlas of charts U → X defining local coordinates on U modeled on X.

- Geometry: Homogeneous space X = G/H.
- Topology: Manifold Σ with universal covering $\widetilde{\Sigma} \longrightarrow \Sigma$ and fundamental group π .
- *Marking:* Diffeomorphism $\Sigma \xrightarrow{f} M$; the geometry on M varies, but the topology of Σ remains fixed.
 - Patches U ⊂ M: Coordinate atlas of charts U → X defining local coordinates on U modeled on X.

On overlapping patches, coordinate changes extend (locally uniquely) to transformations of X from G.

- Geometry: Homogeneous space X = G/H.
- Topology: Manifold Σ with universal covering $\widetilde{\Sigma} \longrightarrow \Sigma$ and fundamental group π .
- *Marking:* Diffeomorphism $\Sigma \xrightarrow{f} M$; the geometry on M varies, but the topology of Σ remains fixed.
 - Patches U ⊂ M: Coordinate atlas of charts U → X defining local coordinates on U modeled on X.
 - On overlapping patches, coordinate changes extend (locally uniquely) to transformations of X from G.
 - Local charts define *development* immersion Σ̃ → X, equivariantly respecting *holonomy* homomorphism π → G.
Coordinate atlases and development

- Geometry: Homogeneous space X = G/H.
- Topology: Manifold Σ with universal covering $\widetilde{\Sigma} \longrightarrow \Sigma$ and fundamental group π .
- *Marking:* Diffeomorphism $\Sigma \xrightarrow{f} M$; the geometry on M varies, but the topology of Σ remains fixed.
 - Patches U ⊂ M: Coordinate atlas of charts U → X defining local coordinates on U modeled on X.
 - On overlapping patches, coordinate changes extend (locally uniquely) to transformations of X from G.
 - Local charts define *development* immersion Σ̃ → X, equivariantly respecting *holonomy* homomorphism π → G.

Development globalizes coordinate charts.

Coordinate atlases and development

- Geometry: Homogeneous space X = G/H.
- Topology: Manifold Σ with universal covering $\widetilde{\Sigma} \longrightarrow \Sigma$ and fundamental group π .
- *Marking:* Diffeomorphism $\Sigma \xrightarrow{f} M$; the geometry on M varies, but the topology of Σ remains fixed.
 - Patches U ⊂ M: Coordinate atlas of charts U → X defining local coordinates on U modeled on X.
 - On overlapping patches, coordinate changes extend (locally uniquely) to transformations of X from G.
 - Local charts define *development* immersion Σ̃ → X, equivariantly respecting *holonomy* homomorphism π → G.
 - Development globalizes coordinate charts.
 - Holonomy globalizes coordinate changes.

▲□▶▲圖▶▲≣▶▲≣▶ ≣ めへぐ

Construct deformation space of marked (G, X)-structures on Σ up to appropriate equivalence relation.

- Construct deformation space of marked (G, X)-structures on Σ up to appropriate equivalence relation.
- Holonomy defines a mapping

$$\mathsf{Def}_{(G,X)}(\Sigma) \xrightarrow{\mathcal{H}} \mathsf{Rep}(\pi,G)$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● ● ●

- Construct deformation space of marked (G, X)-structures on Σ up to appropriate equivalence relation.
- Holonomy defines a mapping

$$\mathsf{Def}_{(G,X)}(\Sigma) \xrightarrow{\mathcal{H}} \mathsf{Rep}(\pi,G)$$

Best cases stratify into smooth manifolds and H "tries to be" local diffeomorphism (Thurston 1979).

- Construct deformation space of marked (G, X)-structures on Σ up to appropriate equivalence relation.
- Holonomy defines a mapping

$$\mathsf{Def}_{(G,X)}(\Sigma) \xrightarrow{\mathcal{H}} \mathsf{Rep}(\pi,G)$$

 Best cases stratify into smooth manifolds and H "tries to be" local diffeomorphism (Thurston 1979).

 Changing marking corresponds to action of mapping class group on Def_(G,X)(Σ)

- Construct deformation space of marked (G, X)-structures on Σ up to appropriate equivalence relation.
- Holonomy defines a mapping

$$\mathsf{Def}_{(G,X)}(\Sigma) \xrightarrow{\mathcal{H}} \mathsf{Rep}(\pi,G)$$

 Best cases stratify into smooth manifolds and H "tries to be" local diffeomorphism (Thurston 1979).

- Changing marking corresponds to action of mapping class group on Def_(G,X)(Σ)
- Orbits comprise moduli space of (unmarked) (G, X)-structures on Σ.

- Construct deformation space of marked (G, X)-structures on Σ up to appropriate equivalence relation.
- Holonomy defines a mapping

$$\mathsf{Def}_{(G,X)}(\Sigma) \xrightarrow{\mathcal{H}} \mathsf{Rep}(\pi,G)$$

- Best cases stratify into smooth manifolds and H "tries to be" local diffeomorphism (Thurston 1979).
- Changing marking corresponds to action of mapping class group on Def_(G,X)(Σ)
- Orbits comprise moduli space of (unmarked) (G, X)-structures on Σ.
 - Analogous to Riemann space $\mathfrak{M}(\Sigma) \longleftrightarrow \mathfrak{T}(\Sigma)/\mathsf{Mod}(\Sigma)$.

◆□ ▶ ◆□ ▶ ◆ 臣 ▶ ◆ 臣 ▶ ○ 臣 ○ の Q @

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ 三三 - のへぐ

►
$$X = H^2$$
, $G = Isom(H^2) \cong PGL(2, \mathbb{R})$:

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ 三三 - のへぐ

- ► $X = H^2$, $G = Isom(H^2) \cong PGL(2, \mathbb{R})$:
 - Then $\operatorname{Def}_{(G,X)}(\Sigma)$ is the *Fricke space* $\mathfrak{F}(\Sigma) \longleftrightarrow \mathfrak{T}(\Sigma)$.
 - Embedding $\mathfrak{F}(\Sigma) \xrightarrow{\mathcal{H}} \operatorname{Rep}(\pi, G)$ as connected component:

・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・

X = H², G = Isom(H²) ≅ PGL(2, ℝ):
 Then Def_(G,X)(Σ) is the *Fricke space* 𝔅(Σ) ↔ 𝔅(Σ).
 Embedding 𝔅(Σ) → Rep(π, G) as connected component:
 Trivial dynamics: Action of Mod(Σ) on 𝔅(Σ) is proper.

X = H², G = Isom(H²) ≅ PGL(2, ℝ):
 Then Def_(G,X)(Σ) is the *Fricke space* 𝔅(Σ) ↔ 𝔅(Σ).
 Embedding 𝔅(Σ) → Rep(π, G) as connected component:
 Trivial dynamics: Action of Mod(Σ) on 𝔅(Σ) is proper.
 Quotient identifies with the *Riemann moduli space* 𝔅(Σ).

X = H², G = Isom(H²) ≅ PGL(2, ℝ):
Then Def_(G,X)(Σ) is the *Fricke space* 𝔅(Σ) ↔ 𝔅(Σ).
Embedding 𝔅(Σ) → Rep(π, G) as connected component: *Trivial dynamics:* Action of Mod(Σ) on 𝔅(Σ) is proper.
Quotient identifies with the *Riemann moduli space* 𝔅(Σ).
For Σ = T², the deformation space of unit-area Euclidean structures identifies with the upper half-plane H².

X = H², G = Isom(H²) ≅ PGL(2, ℝ):
Then Def_(G,X)(Σ) is the *Fricke space* 𝔅(Σ) ↔ 𝔅(Σ).
Embedding 𝔅(Σ) → Rep(π, G) as connected component: *Trivial dynamics:* Action of Mod(Σ) on 𝔅(Σ) is proper.
Quotient identifies with the *Riemann moduli space* 𝔅(Σ).
For Σ = T² the deformation space of unit-area Euclidean

For Σ = T², the deformation space of unit-area Euclidean structures identifies with the upper half-plane H².

Modular group Mod(Σ) ≅ GL(2, Z) acts properly by linear fractional transformations on H².

・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・



Proper (trivial) dynamics: PGL(2, $\mathbb{Z})\text{-}action$ on H^2

▲ロ ▶ ▲周 ▶ ▲ 国 ▶ ▲ 国 ▶ ● の Q @



Proper (trivial) dynamics: PGL(2, \mathbb{Z})-action on H²

For Σ = T², the deformation space of unit-area Euclidean structures is the upper half-plane H² with action the modular group Mod(Σ) ≅ GL(2, ℤ) acting *properly* by linear fractional transformations.



Proper (trivial) dynamics: PGL(2, $\mathbb{Z})\text{-}action$ on H^2

- For Σ = T², the deformation space of unit-area Euclidean structures is the upper half-plane H² with action the modular group Mod(Σ) ≅ GL(2, ℤ) acting *properly* by linear fractional transformations.
- If χ(Σ) < 0, my work with Suhyoung Choi implies Mod(Σ) acts properly on the deformation space ℝP²(S) of marked real projective structures.



Proper (trivial) dynamics:PGL(2, $\mathbb{Z})\text{-}action$ on H^2

- For Σ = T², the deformation space of unit-area Euclidean structures is the upper half-plane H² with action the modular group Mod(Σ) ≅ GL(2, ℤ) acting *properly* by linear fractional transformations.
- If χ(Σ) < 0, my work with Suhyoung Choi implies Mod(Σ) acts properly on the deformation space ℝP²(S) of marked real projective structures.
- In contrast, complete affine structures on with usual linear action of GL(2, ℤ). (O. Baues 2000).







• Euclidean structures $T^2 \xrightarrow{f} \mathbb{R}^2 / \Lambda$ are all *affinely isomorphic* and correspond to the origin $0 \in \mathbb{R}^2$.

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ ▲ 三 ● ● ●



• Euclidean structures $T^2 \xrightarrow{f} \mathbb{R}^2 / \Lambda$ are all affinely isomorphic and correspond to the origin $0 \in \mathbb{R}^2$.

Others obtained from the polynomial diffeomorphism

$$\mathbb{R}^2 \xrightarrow{\phi} \mathbb{R}^2$$

 $(x,y) \longmapsto (x+y^2,y)$

as $T^2 \xrightarrow{\cong} \mathbb{R}^2/\phi \Lambda \phi^{-1}$. (Kuiper 1950)



- Euclidean structures $T^2 \xrightarrow{f} \mathbb{R}^2 / \Lambda$ are all affinely isomorphic and correspond to the origin $0 \in \mathbb{R}^2$.
- Others obtained from the polynomial diffeomorphism

$$\mathbb{R}^2 \xrightarrow{\phi} \mathbb{R}^2$$
$$(x, y) \longmapsto (x + y^2, y)$$

as $T^2 \xrightarrow{\cong} \mathbb{R}^2/\phi \Lambda \phi^{-1}$. (Kuiper 1950)

▶ If translation $\lambda(x, y) = (x + s, y + t)$ lies in the lattice Λ , then

$$(x, y) \xrightarrow{\phi\lambda\phi^{-1}} (x + 2ty + (s + t^2), y + t)$$

is affine.

(ロ)、

The twisted cubic cone

Baues showed that these correspond to *invariant* affine structures on the torus *as a Lie group*.

The twisted cubic cone

- Baues showed that these correspond to *invariant* affine structures on the torus *as a Lie group*.
- Deligne (2021: This deformation space is naturally a *twisted* cubic cone

$$\bigg\{ [X:Y:Z:W] \in \mathbb{R}^4 \ \bigg| \ XZ - Y^2 = YW - Z^2 = 0 \bigg\},$$

the image of the $GL(2,\mathbb{Z})$ -equivariant Veronese embedding







ヘロト 人間 とくほとくほとう

æ



▶ The linear action of $Mod(T^2) \cong GL(2, \mathbb{Z})$ on \mathbb{R}^2 is chaotic — no reasonable quotient.

▲□▶ ▲□▶ ▲三▶ ▲三▶ 三三 のへで



▶ The linear action of $Mod(T^2) \cong GL(2, \mathbb{Z})$ on \mathbb{R}^2 is chaotic — no reasonable quotient.

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ ▲ 三 ● ● ●

• Euclidean area on \mathbb{R}^2 is invariant.



▶ The linear action of $Mod(T^2) \cong GL(2, \mathbb{Z})$ on \mathbb{R}^2 is chaotic — no reasonable quotient.

▲□▶ ▲□▶ ▲三▶ ▲三▶ 三三 のへの

- Euclidean area on \mathbb{R}^2 is invariant.
- Moore 1966) Action is ergodic:



▶ The linear action of $Mod(T^2) \cong GL(2, \mathbb{Z})$ on \mathbb{R}^2 is chaotic — no reasonable quotient.

▲□▶ ▲□▶ ▲□▶ ▲□▶ □ のQで

- Euclidean area on \mathbb{R}^2 is invariant.
- Moore 1966) Action is ergodic:
 - Every invariant function is a.e. constant.



▶ The linear action of $Mod(T^2) \cong GL(2, \mathbb{Z})$ on \mathbb{R}^2 is chaotic — no reasonable quotient.

▲□▶ ▲□▶ ▲□▶ ▲□▶ □ のQで

- Euclidean area on \mathbb{R}^2 is invariant.
- Moore 1966) Action is ergodic:
 - Every invariant function is a.e. constant.
 - Almost every orbit is dense.



- ▶ The linear action of $Mod(T^2) \cong GL(2, \mathbb{Z})$ on \mathbb{R}^2 is chaotic no reasonable quotient.
 - Euclidean area on \mathbb{R}^2 is invariant.
 - Moore 1966) Action is ergodic:
 - Every invariant function is a.e. constant.
 - Almost every orbit is dense.
 - ... although discrete orbits exist, e.g. $\frac{1}{n}\mathbb{Z}^2$...

▲□▶ ▲□▶ ▲三▶ ▲三▶ 三三 のへの



- ▶ The linear action of $Mod(T^2) \cong GL(2, \mathbb{Z})$ on \mathbb{R}^2 is chaotic no reasonable quotient.
 - Euclidean area on \mathbb{R}^2 is invariant.
 - Moore 1966) Action is ergodic:
 - Every invariant function is a.e. constant.
 - Almost every orbit is dense.
 - ... although discrete orbits exist, e.g. $\frac{1}{n}\mathbb{Z}^2$...
- Therefore, the classification of geometric structures should be more insightfully regarded as a *dynamical system*, since the moduli space — its quotient — is often intractable.

Character functions and Hamiltonian twist flows

▲□▶▲圖▶▲≣▶▲≣▶ ≣ のへぐ
Character functions and Hamiltonian twist flows

Elements γ ∈ π₁(Σ) define *character functions* on Rep:

$$\mathsf{Rep}(\pi, G) \xrightarrow{f_{\gamma}} \mathbb{R}$$
$$[\rho] \mapsto \Re(\mathsf{Tr}\rho(\gamma))$$

with Hamiltonian vector fields $Ham(f_{\gamma})$.

Character functions and Hamiltonian twist flows

Elements γ ∈ π₁(Σ) define character functions on Rep:

$$\mathsf{Rep}(\pi, G) \xrightarrow{f_{\gamma}} \mathbb{R} \ [
ho] \mapsto \Re(\mathsf{Tr}
ho(\gamma))$$

with Hamiltonian vector fields $Ham(f_{\gamma})$.

For the Fricke-Teichmüller component when G = PSL(2, ℝ), γ corresponding to a simple loop, Ham(f_γ) generates the Fenchel-Nielsen twist flows, (Wolpert 1982).

Character functions and Hamiltonian twist flows

Elements $\gamma \in \pi_1(\Sigma)$ define *character functions* on Rep:

$$\mathsf{Rep}(\pi, G) \xrightarrow{f_{\gamma}} \mathbb{R} \ [
ho] \mapsto \Re(\mathsf{Tr}
ho(\gamma))$$

with Hamiltonian vector fields $Ham(f_{\gamma})$.

- For the Fricke-Teichmüller component when G = PSL(2, ℝ), γ corresponding to a simple loop, Ham(f_γ) generates the Fenchel-Nielsen twist flows, (Wolpert 1982).
- For G = SL(2), character functions f_γ of simple γ generate coordinate ring of Rep(π, G).

▲□▶▲圖▶▲≣▶▲≣▶ ≣ めぬぐ

Let G = SU(2). Dehn twist Tw_γ generates lattice inside R-action corresponding to Ham(f_γ)-orbits.

Let G = SU(2). Dehn twist Tw_γ generates lattice inside R-action corresponding to Ham(f_γ)-orbits.

• $\rho(\gamma) \in G$ elliptic \Longrightarrow Integral curves of $\operatorname{Ham}(f_{\gamma})$ are circles C_{ρ}^{γ} .

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● ● ●

Let G = SU(2). Dehn twist Tw_γ generates lattice inside R-action corresponding to Ham(f_γ)-orbits.

• $\rho(\gamma) \in G$ elliptic \Longrightarrow Integral curves of $\operatorname{Ham}(f_{\gamma})$ are circles C_{ρ}^{γ} .

For almost every value of f_γ, the Dehn twist Tw_γ defines ergodic translation of C^γ_ρ.

Let G = SU(2). Dehn twist Tw_γ generates lattice inside R-action corresponding to Ham(f_γ)-orbits.

• $\rho(\gamma) \in G$ elliptic \Longrightarrow Integral curves of $\operatorname{Ham}(f_{\gamma})$ are circles C_{ρ}^{γ} .

- For almost every value of f_γ, the Dehn twist Tw_γ defines ergodic translation of C^γ_ρ.
- Ergodic decomposition: Every Tw_γ-invariant function is a.e. Ham(f_γ)-invariant.

Let G = SU(2). Dehn twist Tw_γ generates lattice inside R-action corresponding to Ham(f_γ)-orbits.

• $\rho(\gamma) \in G$ elliptic \Longrightarrow Integral curves of $\operatorname{Ham}(f_{\gamma})$ are circles C_{ρ}^{γ} .

- For almost every value of f_{γ} , the Dehn twist Tw_{γ} defines ergodic translation of C_{ρ}^{γ} .
- Ergodic decomposition: Every Tw_γ-invariant function is a.e. Ham(f_γ)-invariant.
 - If f_γ generate the coordinate ring of Rep(π, G), their differentials df_γ span every cotangent space.

Let G = SU(2). Dehn twist Tw_γ generates lattice inside R-action corresponding to Ham(f_γ)-orbits.

• $\rho(\gamma) \in G$ elliptic \Longrightarrow Integral curves of $Ham(f_{\gamma})$ are circles C_{ρ}^{γ} .

- For almost every value of f_γ, the Dehn twist Tw_γ defines ergodic translation of C^γ_ρ.
- Ergodic decomposition: Every Tw_γ-invariant function is a.e. Ham(f_γ)-invariant.
 - If f_γ generate the coordinate ring of Rep(π, G), their differentials df_γ span every cotangent space.
 - Ham (f_{γ}) span every tangent space.

Let G = SU(2). Dehn twist Tw_γ generates lattice inside R-action corresponding to Ham(f_γ)-orbits.

- $\rho(\gamma) \in G$ elliptic \Longrightarrow Integral curves of $Ham(f_{\gamma})$ are circles C_{ρ}^{γ} .
- For almost every value of f_γ, the Dehn twist Tw_γ defines ergodic translation of C^γ_ρ.
- Ergodic decomposition: Every Tw_γ-invariant function is a.e. Ham(f_γ)-invariant.
 - If f_γ generate the coordinate ring of Rep(π, G), their differentials df_γ span every cotangent space.
 - Ham (f_{γ}) span every tangent space.
 - Flows of Ham(f_γ) generate transitive action on each connected component of where the vector fields span.

Let G = SU(2). Dehn twist Tw_γ generates lattice inside R-action corresponding to Ham(f_γ)-orbits.

- $\rho(\gamma) \in G$ elliptic \Longrightarrow Integral curves of $\operatorname{Ham}(f_{\gamma})$ are circles C_{ρ}^{γ} .
- For almost every value of f_γ, the Dehn twist Tw_γ defines ergodic translation of C^γ_ρ.
- Ergodic decomposition: Every Tw_γ-invariant function is a.e. Ham(f_γ)-invariant.
 - If f_γ generate the coordinate ring of Rep(π, G), their differentials df_γ span every cotangent space.
 - Ham (f_{γ}) span every tangent space.
 - Flows of Ham(f_γ) generate transitive action on each connected component of where the vector fields span.
- Mod(Σ)-action ergodic on regions where simple loops have elliptic holonomy.

Vogt-Fricke theorem and F_2

Vogt-Fricke theorem and F₂

• Let
$$F_2 = \langle X, Y \rangle$$
 be free of rank two. Then

 $\mathsf{Hom}(\mathsf{F}_2,\mathsf{SL}(2))\cong\mathsf{SL}(2)\times\mathsf{SL}(2)$

and $\text{Rep}(F_2, SL(2))$ is its quotient under Inn(SL(2)).

Vogt-Fricke theorem and F₂

• Let
$$F_2 = \langle X, Y \rangle$$
 be free of rank two. Then

 $\mathsf{Hom}(\mathsf{F}_2,\mathsf{SL}(2))\cong\mathsf{SL}(2)\times\mathsf{SL}(2)$

and Rep(F₂, SL(2)) is its quotient under Inn(SL(2)).
 The Inn(SL(2))-invariant mapping

$$\operatorname{Hom}(\mathsf{F}_{2}, \mathsf{SL}(2)) \longrightarrow \mathbb{C}^{3}$$
$$\rho \longmapsto \begin{bmatrix} \xi := & \operatorname{Tr}(\rho(X)) \\ \eta := & \operatorname{Tr}(\rho(Y)) \\ \zeta := & \operatorname{Tr}(\rho(XY)) \end{bmatrix}$$

defines an isomorphism

$$\operatorname{Rep}(F_2, \operatorname{SL}(2)) \xrightarrow{\cong} \mathbb{C}^3.$$

Out(F₂)-invariant commutator trace function:

$$\mathsf{Rep}(\mathsf{F}_2,\mathsf{SL}(2)) \cong \mathbb{C}^3 \xrightarrow{\kappa} \mathbb{C}$$
$$(\xi,\eta,\zeta) \longmapsto \xi^2 + \eta^2 + \zeta^2 - \xi\eta\zeta - 2$$
$$= \mathsf{Tr}[\rho(X),\rho(Y)]$$

Out(F₂)-invariant commutator trace function:

$$\mathsf{Rep}(\mathsf{F}_2,\mathsf{SL}(2)) \cong \mathbb{C}^3 \xrightarrow{\kappa} \mathbb{C}$$
$$(\xi,\eta,\zeta) \longmapsto \xi^2 + \eta^2 + \zeta^2 - \xi\eta\zeta - 2$$
$$= \mathsf{Tr}[\rho(X),\rho(Y)]$$

(Nielsen): Every automorphism of F₂ maps [X, Y] to a conjugate of itself or its inverse.

Out(F₂)-invariant commutator trace function:

$$\mathsf{Rep}(\mathsf{F}_2,\mathsf{SL}(2)) \cong \mathbb{C}^3 \xrightarrow{\kappa} \mathbb{C}$$
$$(\xi,\eta,\zeta) \longmapsto \xi^2 + \eta^2 + \zeta^2 - \xi\eta\zeta - 2$$
$$= \mathsf{Tr}[\rho(X),\rho(Y)]$$

- (Nielsen): Every automorphism of F₂ maps [X, Y] to a conjugate of itself or its inverse.
 - Every homotopy-equivalence $\Sigma_{1,1} \rightsquigarrow \Sigma_{1,1}$ is homotopic to homeomorphism of $\Sigma_{1,1}$.

Out(F₂)-invariant commutator trace function:

$$\mathsf{Rep}(\mathsf{F}_2,\mathsf{SL}(2)) \cong \mathbb{C}^3 \xrightarrow{\kappa} \mathbb{C}$$
$$(\xi,\eta,\zeta) \longmapsto \xi^2 + \eta^2 + \zeta^2 - \xi\eta\zeta - 2$$
$$= \mathsf{Tr}[\rho(X),\rho(Y)]$$

- (Nielsen): Every automorphism of F₂ maps [X, Y] to a conjugate of itself or its inverse.
 - Every homotopy-equivalence $\Sigma_{1,1} \rightsquigarrow \Sigma_{1,1}$ is homotopic to homeomorphism of $\Sigma_{1,1}$.

・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・

• $Mod(\Sigma) \cong Out(\pi)$, just like closed surfaces.

Out(F₂)-invariant commutator trace function:

$$\mathsf{Rep}(\mathsf{F}_2,\mathsf{SL}(2)) \cong \mathbb{C}^3 \xrightarrow{\kappa} \mathbb{C}$$
$$(\xi,\eta,\zeta) \longmapsto \xi^2 + \eta^2 + \zeta^2 - \xi\eta\zeta - 2$$
$$= \mathsf{Tr}[\rho(X),\rho(Y)]$$

- (Nielsen): Every automorphism of F₂ maps [X, Y] to a conjugate of itself or its inverse.
 - Every homotopy-equivalence $\Sigma_{1,1} \rightsquigarrow \Sigma_{1,1}$ is homotopic to homeomorphism of $\Sigma_{1,1}$.

・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・

• $Mod(\Sigma) \cong Out(\pi)$, just like closed surfaces.

•
$$\mathsf{Out}(\mathsf{F}_2) \cong \mathsf{GL}(2,\mathbb{Z}) = \mathsf{Mod}(\Sigma_{1,1})$$

Out(F₂)-invariant commutator trace function:

$$\mathsf{Rep}(\mathsf{F}_2,\mathsf{SL}(2)) \cong \mathbb{C}^3 \xrightarrow{\kappa} \mathbb{C}$$
$$(\xi,\eta,\zeta) \longmapsto \xi^2 + \eta^2 + \zeta^2 - \xi\eta\zeta - 2$$
$$= \mathsf{Tr}[\rho(X),\rho(Y)]$$

- (Nielsen): Every automorphism of F₂ maps [X, Y] to a conjugate of itself or its inverse.
 - Every homotopy-equivalence Σ_{1,1} → Σ_{1,1} is homotopic to homeomorphism of Σ_{1,1}.

• $Mod(\Sigma) \cong Out(\pi)$, just like closed surfaces.

•
$$\mathsf{Out}(\mathsf{F}_2) \cong \mathsf{GL}(2,\mathbb{Z}) = \mathsf{Mod}(\Sigma_{1,1})$$

This isomorphism with C³ depends on a superbasis of F₂: an isomorphism F₂ ≅ ⟨X, Y, Z | XYZ = 1⟩.

Out(F₂)-invariant commutator trace function:

$$\mathsf{Rep}(\mathsf{F}_2,\mathsf{SL}(2)) \cong \mathbb{C}^3 \xrightarrow{\kappa} \mathbb{C}$$
$$(\xi,\eta,\zeta) \longmapsto \xi^2 + \eta^2 + \zeta^2 - \xi\eta\zeta - 2$$
$$= \mathsf{Tr}[\rho(X),\rho(Y)]$$

- (Nielsen): Every automorphism of F₂ maps [X, Y] to a conjugate of itself or its inverse.
 - Every homotopy-equivalence $\Sigma_{1,1} \rightsquigarrow \Sigma_{1,1}$ is homotopic to homeomorphism of $\Sigma_{1,1}$.

• $Mod(\Sigma) \cong Out(\pi)$, just like closed surfaces.

- $\blacktriangleright \ \mathsf{Out}(\mathsf{F}_2)\cong\mathsf{GL}(2,\mathbb{Z})=\mathsf{Mod}(\Sigma_{1,1})$
- This isomorphism with C³ depends on a superbasis of F₂: an isomorphism F₂ ≅ ⟨X, Y, Z | XYZ = 1⟩.
 - Superbases are vertices in the Markoff-Bowditch tree associated to the character variety of F₂.

◆□▶ ◆□▶ ◆目▶ ◆目▶ 目 りへぐ

The boundary trace

$$\kappa(\xi,\eta,\zeta) := \xi^2 + \eta^2 + \zeta^2 - \xi\eta\zeta - 2$$

determines the Poisson structure on \mathbb{C}^3 defined by bivector

$$egin{aligned} &d\kappa\cdot\partial_{\xi}\wedge\partial_{\eta}\wedge\partial_{\zeta}\ &=(2\xi-\eta\zeta)\;\partial_{\eta}\wedge\partial_{\zeta}\ &+(2\eta-\zeta\xi)\;\partial_{\zeta}\wedge\partial_{\xi}\ &+(2\zeta-\xi\eta)\;\partial_{\xi}\wedge\partial_{\eta}. \end{aligned}$$

(ロ)、(型)、(E)、(E)、 E) の(()

The boundary trace

$$\kappa(\xi,\eta,\zeta) := \xi^2 + \eta^2 + \zeta^2 - \xi\eta\zeta - 2$$

determines the Poisson structure on \mathbb{C}^3 defined by bivector

$$egin{aligned} &d\kappa\cdot\partial_{\xi}\wedge\partial_{\eta}\wedge\partial_{\zeta}\ &=(2\xi-\eta\zeta)\;\partial_{\eta}\wedge\partial_{\zeta}\ &+(2\eta-\zeta\xi)\;\partial_{\zeta}\wedge\partial_{\xi}\ &+(2\zeta-\xi\eta)\;\partial_{\xi}\wedge\partial_{\eta}. \end{aligned}$$

Symplectic structure on level sets $\kappa^{-1}(k)$ include:

The boundary trace

$$\kappa(\xi,\eta,\zeta) := \xi^2 + \eta^2 + \zeta^2 - \xi\eta\zeta - 2$$

determines the Poisson structure on \mathbb{C}^3 defined by bivector

$$egin{aligned} &d\kappa\cdot\partial_{\xi}\wedge\partial_{\eta}\wedge\partial_{\zeta}\ &=(2\xi-\eta\zeta)\;\partial_{\eta}\wedge\partial_{\zeta}\ &+(2\eta-\zeta\xi)\;\partial_{\zeta}\wedge\partial_{\xi}\ &+(2\zeta-\xi\eta)\;\partial_{\xi}\wedge\partial_{\eta}. \end{aligned}$$

- Symplectic structure on level sets $\kappa^{-1}(k)$ include:
 - Weil-Petersson symplectic structure on Fricke spaces $k \leq -2$;

The boundary trace

$$\kappa(\xi,\eta,\zeta) := \xi^2 + \eta^2 + \zeta^2 - \xi\eta\zeta - 2$$

determines the Poisson structure on \mathbb{C}^3 defined by bivector

$$egin{aligned} &d\kappa\cdot\partial_{\xi}\wedge\partial_{\eta}\wedge\partial_{\zeta}\ &=(2\xi-\eta\zeta)\;\partial_{\eta}\wedge\partial_{\zeta}\ &+(2\eta-\zeta\xi)\;\partial_{\zeta}\wedge\partial_{\xi}\ &+(2\zeta-\xi\eta)\;\partial_{\xi}\wedge\partial_{\eta}. \end{aligned}$$

- Symplectic structure on level sets $\kappa^{-1}(k)$ include:
 - Weil-Petersson symplectic structure on Fricke spaces $k \leq -2$;
 - Narasimhan-Atiyah-Bott structure for G = SU(2).

The boundary trace

$$\kappa(\xi,\eta,\zeta) := \xi^2 + \eta^2 + \zeta^2 - \xi\eta\zeta - 2$$

determines the Poisson structure on \mathbb{C}^3 defined by bivector

$$egin{aligned} &d\kappa\cdot\partial_{\xi}\wedge\partial_{\eta}\wedge\partial_{\zeta}\ &=(2\xi-\eta\zeta)\;\partial_{\eta}\wedge\partial_{\zeta}\ &+(2\eta-\zeta\xi)\;\partial_{\zeta}\wedge\partial_{\xi}\ &+(2\zeta-\xi\eta)\;\partial_{\xi}\wedge\partial_{\eta}. \end{aligned}$$

Symplectic structure on level sets κ⁻¹(k) include:
 Weil-Petersson symplectic structure on Fricke spaces k ≤ -2;
 Narasimhan-Atiyah-Bott structure for G = SU(2).
 κ⁻¹(k) are the *relative character varieties*.

◆□▶◆□▶◆≧▶◆≧▶ ≧ りへぐ

Nonlinear automorphisms of

$$\kappa(\xi,\eta,\zeta) = \xi^2 + \eta^2 + \zeta^2 - \xi\eta\zeta - 2 = k$$

generated by involutions:

$$\begin{bmatrix} \xi \\ \eta \\ \zeta \end{bmatrix} \longmapsto \begin{bmatrix} \eta \zeta - \xi \\ \eta \\ \zeta \end{bmatrix}, \quad \begin{bmatrix} \xi \\ \eta \\ \zeta \end{bmatrix} \longmapsto \begin{bmatrix} \xi \\ \xi \zeta - \eta \\ \zeta \end{bmatrix}, \quad \begin{bmatrix} \xi \\ \eta \\ \zeta \end{bmatrix} \longmapsto \begin{bmatrix} \xi \\ \eta \\ \xi \eta - \zeta \end{bmatrix}$$

(ロ)、(型)、(E)、(E)、 E) の(()

Nonlinear automorphisms of

$$\kappa(\xi,\eta,\zeta) = \xi^2 + \eta^2 + \zeta^2 - \xi\eta\zeta - 2 = k$$

generated by involutions:

$$\begin{bmatrix} \xi \\ \eta \\ \zeta \end{bmatrix} \longmapsto \begin{bmatrix} \eta \zeta - \xi \\ \eta \\ \zeta \end{bmatrix}, \quad \begin{bmatrix} \xi \\ \eta \\ \zeta \end{bmatrix} \longmapsto \begin{bmatrix} \xi \\ \xi \zeta - \eta \\ \zeta \end{bmatrix}, \quad \begin{bmatrix} \xi \\ \eta \\ \zeta \end{bmatrix} \longmapsto \begin{bmatrix} \xi \\ \eta \\ \xi \eta - \zeta \end{bmatrix}$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● ● ●

 Coordinate projections C³ → C² branched double coverings; involutions are deck transformations.

Nonlinear automorphisms of

$$\kappa(\xi,\eta,\zeta) = \xi^2 + \eta^2 + \zeta^2 - \xi\eta\zeta - 2 = k$$

generated by involutions:

$$\begin{bmatrix} \xi \\ \eta \\ \zeta \end{bmatrix} \longmapsto \begin{bmatrix} \eta \zeta - \xi \\ \eta \\ \zeta \end{bmatrix}, \quad \begin{bmatrix} \xi \\ \eta \\ \zeta \end{bmatrix} \longmapsto \begin{bmatrix} \xi \\ \xi \zeta - \eta \\ \zeta \end{bmatrix}, \quad \begin{bmatrix} \xi \\ \eta \\ \zeta \end{bmatrix} \longmapsto \begin{bmatrix} \xi \\ \eta \\ \xi \eta - \zeta \end{bmatrix}$$

 Coordinate projections C³ → C² branched double coverings; involutions are deck transformations.

Fixing η and ζ yields quadratic equation in ξ ;

$$\xi^2 - (\eta \zeta) \xi = k + 2 - \eta^2 - \zeta^2$$

whose roots ξ and $\xi' = \eta \zeta - \xi$ sum to linear coefficient $\eta \zeta$.

Cayley cubic $\xi^2 + \eta^2 + \zeta^2 - \xi \eta \zeta = 4$



Cayley cubic $\xi^2 + \eta^2 + \zeta^2 - \xi \eta \zeta = 4$

• Reducible representations correspond precisely to $\kappa^{-1}(2)$.



Cayley cubic $\xi^2 + \eta^2 + \zeta^2 - \xi \eta \zeta = 4$

Reducible representations correspond precisely to κ⁻¹(2).
 Quotient of C* × C* by the involution

$$(a, b) \longmapsto (a^{-1}, b^{-1}).$$

 $\xi = a + a^{-1}, \qquad \eta = b + b^{-1}, \qquad \zeta = ab + (ab)^{-1}$


Cayley cubic $\xi^2 + \eta^2 + \zeta^2 - \xi \eta \zeta = 4$

• Reducible representations correspond precisely to $\kappa^{-1}(2)$.

• Quotient of $\mathbb{C}^* \times \mathbb{C}^*$ by the involution

$$(a,b)\mapsto (a^{-1},b^{-1}).$$

 $\xi = a + a^{-1}, \qquad \eta = b + b^{-1}, \qquad \zeta = ab + (ab)^{-1}$

• Homogeneous dynamics: $GL(2,\mathbb{Z})$ -action on $(\mathbb{C}^* \times \mathbb{C}^*)/(\mathbb{Z}/2)$.



\mathbb{R} -points: Unitary representations



\mathbb{R} -points: Unitary representations

▶ R-points correspond to representations into R-forms of SL(2): either SL(2, R) or SU(2).



\mathbb{R} -points: Unitary representations

- ▶ ℝ-points correspond to representations into ℝ-forms of SL(2): either SL(2, ℝ) or SU(2).
- Characters in $[-2,2]^3$ with $\kappa \leq 2 \iff SU(2)$ -representations.



► Hyperbolic three-holed spheres parametrized by boundary lengths ℓ_X, ℓ_Y, ℓ_Z ≥ 0

$$\begin{split} \xi &:= -2\cosh\left(\ell_X/2\right)\right) \leq -2\\ \eta &:= -2\cosh\left(\ell_Y/2\right)\right) \leq -2\\ \zeta &:= -2\cosh\left(\ell_Z/2\right)\right) \leq -2 \end{split}$$

► Hyperbolic three-holed spheres parametrized by boundary lengths ℓ_X, ℓ_Y, ℓ_Z ≥ 0

$$\begin{split} \xi &:= -2\cosh\left(\ell_X/2\right)\right) \leq -2\\ \eta &:= -2\cosh\left(\ell_Y/2\right)\right) \leq -2\\ \zeta &:= -2\cosh\left(\ell_Z/2\right)\right) \leq -2 \end{split}$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

• Necessarily $k = \kappa(\xi, \eta, \zeta) \ge 18 = \kappa(-2, -2, -2).$

► Hyperbolic three-holed spheres parametrized by boundary lengths ℓ_X, ℓ_Y, ℓ_Z ≥ 0

$$\begin{split} \xi &:= -2\cosh\left(\ell_X/2\right)\right) \leq -2\\ \eta &:= -2\cosh\left(\ell_Y/2\right)\right) \leq -2\\ \zeta &:= -2\cosh\left(\ell_Z/2\right)\right) \leq -2 \end{split}$$

- Necessarily $k = \kappa(\xi, \eta, \zeta) \ge 18 = \kappa(-2, -2, -2).$
- (-2, -2, -2) corresponds to the complete finite-area
 3-punctured sphere.

► Hyperbolic three-holed spheres parametrized by boundary lengths ℓ_X, ℓ_Y, ℓ_Z ≥ 0

$$\begin{split} \xi &:= -2\cosh\left(\ell_X/2\right)\right) \leq -2\\ \eta &:= -2\cosh\left(\ell_Y/2\right)\right) \leq -2\\ \zeta &:= -2\cosh\left(\ell_Z/2\right)\right) \leq -2 \end{split}$$

- Necessarily $k = \kappa(\xi, \eta, \zeta) \ge 18 = \kappa(-2, -2, -2).$
- (-2, -2, -2) corresponds to the complete finite-area
 3-punctured sphere.
- ► Homotopy-equivalences $\Sigma_{1,1} \rightsquigarrow \Sigma_{0,3}$ (and other surfaces with $\pi_1 \cong F_2$) form wandering domains for $Out(F_2)$ -action.

・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・

Example: The Markoff surface $x^2 + y^2 + z^2 = xyz$



 $\mathbb{R}^3 \cap \kappa^{-1}(-2)$ parametrizes hyperbolic structures on the punctured torus. The origin (0,0,0) corresponds to the unique SU(2)-representation with k = -2. The famous *Markoff triples* correspond to triply symmetric hyperbolic punctured tori.

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □

◆□ ▶ ◆□ ▶ ◆ 臣 ▶ ◆ 臣 ▶ ○ 臣 ○ のへで

► Homotopy equivalences $\Sigma_{1,1} \rightsquigarrow \Sigma_{0,3}$ define embeddings $\mathfrak{F}(\Sigma_{0,3})_k \hookrightarrow \kappa^{-1}(k)$ for k > 18;

► Homotopy equivalences $\Sigma_{1,1} \rightsquigarrow \Sigma_{0,3}$ define embeddings $\mathfrak{F}(\Sigma_{0,3})_k \hookrightarrow \kappa^{-1}(k)$ for k > 18;

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

For $k \leq 18$, action ergodic.

► Homotopy equivalences $\Sigma_{1,1} \rightsquigarrow \Sigma_{0,3}$ define embeddings $\mathfrak{F}(\Sigma_{0,3})_k \hookrightarrow \kappa^{-1}(k)$ for k > 18;

- For $k \leq 18$, action ergodic.
- For k > 18, action ergodic on complement.

- ► Homotopy equivalences $\Sigma_{1,1} \rightsquigarrow \Sigma_{0,3}$ define embeddings $\mathfrak{F}(\Sigma_{0,3})_k \hookrightarrow \kappa^{-1}(k)$ for k > 18;
- For $k \leq 18$, action ergodic.
- For k > 18, action ergodic on complement.
- The level surface k = 18 extends to the famous Clebsch diagonal surface in CP³ defined by:

$$(X_0)^5 + (X_1)^5 + (X_2)^5 + (X_3)^5 + (X_4)^5 = X_0 + X_1 + X_2 + X_3 + X_4 = 0$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

in homogeneous coordinates.

 $x^2 + y^2 + z^2 - xyz = 20$



・ロト ・四ト ・ヨト ・ヨト æ

◆□ ▶ ◆□ ▶ ◆ 臣 ▶ ◆ 臣 ▶ ○ 臣 ○ のへで

 Mod(Σ)-action ergodic on each component Rep(π, G)_τ with respect to the symplectic measure ν. (G-, Pickrell-Xia)

 Mod(Σ)-action ergodic on each component Rep(π, G)_τ with respect to the symplectic measure ν. (G-, Pickrell-Xia)

- Mod(Σ)-action ergodic on each component Rep(π, G)_τ with respect to the symplectic measure ν. (G-, Pickrell-Xia)
 - Ergodic: Only vectors in L²(Rep(π, G)_τ) fixed by Mod(Σ) are constants.

- Mod(Σ)-action ergodic on each component Rep(π, G)_τ with respect to the symplectic measure ν. (G-, Pickrell-Xia)
 - Ergodic: Only vectors in L²(Rep(π, G)_τ) fixed by Mod(Σ) are constants.

Weak-mixing: Only finite-dimensional Mod(Σ)-invariant subspaces on L²(Rep(π, G)_τ) are constants.

- Mod(Σ)-action ergodic on each component Rep(π, G)_τ with respect to the symplectic measure ν. (G-, Pickrell-Xia)
 - Ergodic: Only vectors in L²(Rep(π, G)_τ) fixed by Mod(Σ) are constants.
 - Weak-mixing: Only finite-dimensional Mod(Σ)-invariant subspaces on L²(Rep(π, G)_τ) are constants.
- Other examples of chaotic dynamics occur, even when G is noncompact: (Marché-Wolff 2016) For G = PSL(2, ℝ) and in genus 2, three types of components:

- Mod(Σ)-action ergodic on each component Rep(π, G)_τ with respect to the symplectic measure ν. (G-, Pickrell-Xia)
 - Ergodic: Only vectors in L²(Rep(π, G)_τ) fixed by Mod(Σ) are constants.
 - Weak-mixing: Only finite-dimensional Mod(Σ)-invariant subspaces on L²(Rep(π, G)_τ) are constants.
- Other examples of chaotic dynamics occur, even when G is noncompact: (Marché-Wolff 2016) For G = PSL(2, ℝ) and in genus 2, three types of components:
 - Euler class ±2 (maximal): Fuchsian representations, proper Mod(Σ)-action;

・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・

- Mod(Σ)-action ergodic on each component Rep(π, G)_τ with respect to the symplectic measure ν. (G-, Pickrell-Xia)
 - Ergodic: Only vectors in L²(Rep(π, G)_τ) fixed by Mod(Σ) are constants.
 - Weak-mixing: Only finite-dimensional Mod(Σ)-invariant subspaces on L²(Rep(π, G)_τ) are constants.
- Other examples of chaotic dynamics occur, even when G is noncompact: (Marché-Wolff 2016) For G = PSL(2, ℝ) and in genus 2, three types of components:
 - Euler class ±2 (maximal): Fuchsian representations, proper Mod(Σ)-action;

・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・

Euler class ±1 ergodic Mod(Σ)-action;

- Mod(Σ)-action ergodic on each component Rep(π, G)_τ with respect to the symplectic measure ν. (G-, Pickrell-Xia)
 - Ergodic: Only vectors in L²(Rep(π, G)_τ) fixed by Mod(Σ) are constants.
 - Weak-mixing: Only finite-dimensional Mod(Σ)-invariant subspaces on L²(Rep(π, G)_τ) are constants.
- Other examples of chaotic dynamics occur, even when G is noncompact: (Marché-Wolff 2016) For G = PSL(2, ℝ) and in genus 2, three types of components:
 - Euler class ±2 (maximal): Fuchsian representations, proper Mod(Σ)-action;
 - Euler class ±1 ergodic Mod(Σ)-action;
 - Euler class 0 component singular; two ergodic components.

・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・

- Mod(Σ)-action ergodic on each component Rep(π, G)_τ with respect to the symplectic measure ν. (G-, Pickrell-Xia)
 - Ergodic: Only vectors in L²(Rep(π, G)_τ) fixed by Mod(Σ) are constants.
 - Weak-mixing: Only finite-dimensional Mod(Σ)-invariant subspaces on L²(Rep(π, G)_τ) are constants.
- ► Other examples of chaotic dynamics occur, even when G is noncompact: (Marché-Wolff 2016) For G = PSL(2, ℝ) and in genus 2, three types of components:
 - Euler class ±2 (maximal): Fuchsian representations, proper Mod(Σ)-action;
 - Euler class ±1 ergodic Mod(Σ)-action;
 - Euler class 0 component singular; two ergodic components.

 Main technique for proving ergodicity uses dynamics of Dehn twists in Mod(Σ).

▲□▶▲□▶▲≣▶▲≣▶ ≣ のへの

Flat bundle 𝔅_G(Σ) over 𝔐(Σ) with fibers Rep(π, G) parametrizes these structures as Riemann surface M varies:

$$\mathfrak{E}_{G}(\Sigma) := (\mathfrak{T}(\Sigma) imes \mathsf{Rep}(\pi, G)) / \mathsf{Mod}(\Sigma)$$

 $\mathfrak{M}(\Sigma) := \mathfrak{T}(\Sigma) / \mathsf{Mod}(\Sigma)$

Flat bundle 𝔅_G(Σ) over 𝔐(Σ) with fibers Rep(π, G) parametrizes these structures as Riemann surface M varies:

$$\mathfrak{E}_{G}(\Sigma) := (\mathfrak{T}(\Sigma) imes \mathsf{Rep}(\pi, G)) / \mathsf{Mod}(\Sigma)$$

 $\mathfrak{M}(\Sigma) := \mathfrak{T}(\Sigma) / \mathsf{Mod}(\Sigma)$

Leaves of horizontal foliation *F_G*(Σ) := [*T*(Σ) × {[ρ]}] correspond to Mod(Σ)-orbit Mod(Σ)[ρ] on Rep(π, G).

Flat bundle 𝔅_G(Σ) over 𝔐(Σ) with fibers Rep(π, G) parametrizes these structures as Riemann surface M varies:

$$\mathfrak{E}_{G}(\Sigma) := (\mathfrak{T}(\Sigma) imes \mathsf{Rep}(\pi, G)) / \mathsf{Mod}(\Sigma)$$

 $\mathfrak{M}(\Sigma) := \mathfrak{T}(\Sigma) / \mathsf{Mod}(\Sigma)$

・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・

- Leaves of horizontal foliation *F_G*(Σ) := [*T*(Σ) × {[ρ]}] correspond to Mod(Σ)-orbit Mod(Σ)[ρ] on Rep(*π*, *G*).
- Dynamics of *F_G*(Σ) equivalent to dynamics of action of discrete group Mod(Σ).

 Replace dynamics of Mod(Σ) on Rep(π, G)_τ by a measure-preserving flow Φ on flat bundle UE_G(Σ).

- Replace dynamics of Mod(Σ) on Rep(π, G)_τ by a measure-preserving flow Φ on flat bundle UE_G(Σ).
 - Teichmüller unit sphere bundle UM(Σ) over M(Σ) with Teichmüller geodesic flow φ:

$$U\mathfrak{M}(\Sigma) := U\mathfrak{T}(\Sigma)/\mathsf{Mod}(\Sigma)$$

 $\mathfrak{M}(\Sigma) := \mathfrak{T}(\Sigma)/\mathsf{Mod}(\Sigma)$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ■ ●の00

invariantly stratified; strata fall into components $U^{\sigma}\mathfrak{M}(\Sigma)$.

- Replace dynamics of Mod(Σ) on Rep(π, G)_τ by a measure-preserving flow Φ on flat bundle UE_G(Σ).
 - Teichmüller unit sphere bundle UM(Σ) over M(Σ) with Teichmüller geodesic flow φ:

$$U\mathfrak{M}(\Sigma) := U\mathfrak{T}(\Sigma)/\mathsf{Mod}(\Sigma)$$

 $\mathfrak{M}(\Sigma) := \mathfrak{T}(\Sigma)/\mathsf{Mod}(\Sigma)$

invariantly stratified; strata fall into components $U^{\sigma}\mathfrak{M}(\Sigma)$.

• Insert $\operatorname{Rep}(\pi, G)_{\tau}$ as the fiber:

 $U^{\sigma}_{ au}\mathfrak{E}_{\mathsf{G}}(\Sigma) := \left(U^{\sigma}\mathfrak{T}(\Sigma) imes \mathsf{Rep}(\pi, \mathsf{G})_{ au}\right) / \mathsf{Mod}(\Sigma)$

and horizontally lift ϕ to flow Φ on $U^{\sigma}_{\tau} \mathfrak{E}_{G}(\Sigma)$.

- Replace dynamics of Mod(Σ) on Rep(π, G)_τ by a measure-preserving flow Φ on flat bundle UE_G(Σ).
 - Teichmüller unit sphere bundle UM(Σ) over M(Σ) with Teichmüller geodesic flow φ:

$$U\mathfrak{M}(\Sigma) := U\mathfrak{T}(\Sigma)/\mathsf{Mod}(\Sigma)$$

 $\mathfrak{M}(\Sigma) := \mathfrak{T}(\Sigma)/\mathsf{Mod}(\Sigma)$

invariantly stratified; strata fall into components $U^{\sigma}\mathfrak{M}(\Sigma)$.

• Insert $\operatorname{Rep}(\pi, G)_{\tau}$ as the fiber:

 $U^{\sigma}_{ au}\mathfrak{E}_{G}(\Sigma) := \left(U^{\sigma}\mathfrak{T}(\Sigma) imes \mathsf{Rep}(\pi,G)_{ au}
ight)/\mathsf{Mod}(\Sigma)$

and horizontally lift ϕ to flow Φ on $U^{\sigma}_{\tau}\mathfrak{E}_{G}(\Sigma)$.

Mod(Σ)-dynamics on Rep(π, G) replaced by equivalent action of more tractable (continuous) groups R and SL(2, R).

- Replace dynamics of Mod(Σ) on Rep(π, G)_τ by a measure-preserving flow Φ on flat bundle UE_G(Σ).
 - Teichmüller unit sphere bundle UM(Σ) over M(Σ) with Teichmüller geodesic flow φ:

$$U\mathfrak{M}(\Sigma) := U\mathfrak{T}(\Sigma)/\mathsf{Mod}(\Sigma)$$

 $\mathfrak{M}(\Sigma) := \mathfrak{T}(\Sigma)/\mathsf{Mod}(\Sigma)$

invariantly stratified; strata fall into components $U^{\sigma}\mathfrak{M}(\Sigma)$.

• Insert $\operatorname{Rep}(\pi, G)_{\tau}$ as the fiber:

 $U^{\sigma}_{\tau}\mathfrak{E}_{G}(\Sigma) := (U^{\sigma}\mathfrak{T}(\Sigma) imes \mathsf{Rep}(\pi, G)_{\tau})/\mathsf{Mod}(\Sigma)$

and horizontally lift ϕ to flow Φ on $U^{\sigma}_{\tau}\mathfrak{E}_{G}(\Sigma)$.

- Mod(Σ)-dynamics on Rep(π, G) replaced by equivalent action of more tractable (continuous) groups R and SL(2, R).
- (Forni G) For G compact, Φ strongly mixing on $U^{\sigma}_{\tau}\mathfrak{E}_{G}(\Sigma)$:
Extending Teichmüller geodesic flow

- Replace dynamics of Mod(Σ) on Rep(π, G)_τ by a measure-preserving flow Φ on flat bundle U𝔅_G(Σ).
 - Teichmüller unit sphere bundle UM(Σ) over M(Σ) with Teichmüller geodesic flow φ:

$$U\mathfrak{M}(\Sigma) := U\mathfrak{T}(\Sigma)/\mathsf{Mod}(\Sigma)$$

 $\mathfrak{M}(\Sigma) := \mathfrak{T}(\Sigma)/\mathsf{Mod}(\Sigma)$

invariantly stratified; strata fall into components $U^{\sigma}\mathfrak{M}(\Sigma)$.

• Insert $\operatorname{Rep}(\pi, G)_{\tau}$ as the fiber:

 $U^{\sigma}_{\tau}\mathfrak{E}_{G}(\Sigma) := \left(U^{\sigma}\mathfrak{T}(\Sigma) imes \mathsf{Rep}(\pi, G)_{\tau}\right) / \mathsf{Mod}(\Sigma)$

and horizontally lift ϕ to flow Φ on $U^{\sigma}_{\tau}\mathfrak{E}_{G}(\Sigma)$.

Mod(Σ)-dynamics on Rep(π, G) replaced by equivalent action of more tractable (continuous) groups R and SL(2, R).

(Forni – G) For G compact, Φ strongly mixing on U^σ_τ 𝔅_G(Σ):
μ(g_t(A) ∩ B) → μ(A)μ(B) for A, B measurable and g_t → ∞.

Happy birthday, Giovanni!





문제 문