

Calculus 241, section 11.3 Dot Product

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Here's a basic question: Now that we have sum, difference and scalar multiplication of vectors, is there a way to describe vector times vector multiplication? The answer is, "Yes." In fact, there are two ways.

Definition 11.5: Let $\vec{a} = a_1\vec{i} + a_2\vec{j} + a_3\vec{k}$ and $\vec{b} = b_1\vec{i} + b_2\vec{j} + b_3\vec{k}$ be two vectors.

The **dot product** (or **scalar product** or **inner product**) of \vec{a} and $\vec{b} = \vec{a} \cdot \vec{b} = a_1b_1 + a_2b_2 + a_3b_3$.

Example A. Given $\vec{a} = 4\vec{i} + 2\vec{j} - 6\vec{k}$ and $\vec{b} = \vec{i} + 3\vec{j} - 5\vec{k}$, find $\vec{a} \cdot \vec{b}$.

Important note: The dot product of two vectors is not a vector but a number (scalar).

The expected properties apply to dot products.

Identities: $\vec{a} \cdot \vec{i} = \vec{i} \cdot \vec{a} = a_1$ $\vec{a} \cdot \vec{j} = \vec{j} \cdot \vec{a} = a_2$ $\vec{a} \cdot \vec{k} = \vec{k} \cdot \vec{a} = a_3$

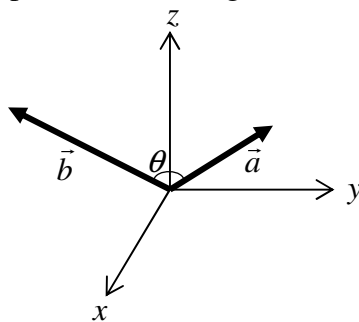
$\vec{i} \cdot \vec{j} = \vec{j} \cdot \vec{k} = \vec{k} \cdot \vec{i} = 0$ $\vec{i} \cdot \vec{i} = \vec{j} \cdot \vec{j} = \vec{k} \cdot \vec{k} = 1$

Commutativity: $\vec{a} \cdot \vec{b} = \vec{b} \cdot \vec{a}$

Associativity: $(c\vec{a}) \cdot \vec{b} = c(\vec{a} \cdot \vec{b}) = \vec{a} \cdot (c\vec{b})$

Distribution $\vec{a} \cdot (\vec{b} + \vec{c}) = \vec{a} \cdot \vec{b} + \vec{a} \cdot \vec{c}$, $(\vec{a} + \vec{b}) \cdot \vec{c} = \vec{a} \cdot \vec{c} + \vec{b} \cdot \vec{c}$

Definition: The **angle** between two nonzero vectors \vec{a} and \vec{b} is defined to be the angle θ , $0 \leq \theta \leq \pi$, formed by the directed line segments whose initial points are the origin.



Theorem 11.6. Let $\vec{a} = a_1\vec{i} + a_2\vec{j} + a_3\vec{k}$ and $\vec{b} = b_1\vec{i} + b_2\vec{j} + b_3\vec{k}$ be two non-zero vectors, and let θ be the angle between \vec{a} and \vec{b} . Then, $\vec{a} \cdot \vec{b} = \|\vec{a}\| \|\vec{b}\| \cos \theta$.

The text does the proof using the Law of Cosines.

To find the angle between nonzero vectors, use $\vec{a} \cdot \vec{b} = \|\vec{a}\| \|\vec{b}\| \cos \theta$ and solve for θ .

Example B. (11.1 A revisited). Given $P = (3, 2, 1)$ and $Q = (-1, 4, -5)$, verify $\overrightarrow{PQ} \cdot \overrightarrow{OQ} = \|\overrightarrow{PQ}\| \|\overrightarrow{OQ}\| \cos \frac{\pi}{6}$ and $\overrightarrow{OQ} \cdot \overrightarrow{OP} = \|\overrightarrow{OQ}\| \|\overrightarrow{OP}\| \cos \frac{\pi}{2}$.

The second dot product above illustrates Corollary 11.7, part a.

Corollary 11.7: a. Two nonzero vectors \mathbf{a} and \mathbf{b} are perpendicular iff $\vec{a} \cdot \vec{b} = 0$.

b. For any vector \vec{a} , $\vec{a} \cdot \vec{a} = \|\vec{a}\|^2$, or equivalently $\|\vec{a}\| = \sqrt{\vec{a} \cdot \vec{a}}$

To prove that two nonzero vectors are perpendicular, it is sufficient to show that $\vec{a} \cdot \vec{b} = 0$.

Definition 11.8. Let \vec{a} be a nonzero vector. The **projection** of a vector \vec{b} onto \vec{a} is the vector $\overrightarrow{\text{pr}_a \vec{b}}$ defined by

$$\overrightarrow{\text{pr}_a \vec{b}} = \left(\frac{\vec{a} \cdot \vec{b}}{\|\vec{a}\|^2} \right) \vec{a}.$$

Note that the projection of \vec{b} onto \vec{a} is a scalar multiple of \vec{a} .

Example A extended. Let $\vec{a} = 4\vec{i} + 2\vec{j} - 6\vec{k}$ and $\vec{b} = 1\vec{i} + 3\vec{j} - 5\vec{k}$. Find $\overrightarrow{\text{pr}_a \vec{b}}$.

Side note: The text develops a simple formula for the norm of a projection, $\|\overrightarrow{\text{pr}_a \vec{b}}\| = \left(\frac{|\vec{a} \cdot \vec{b}|}{\|\vec{a}\|^2} \right) \|\vec{a}\| = \frac{|\vec{a} \cdot \vec{b}|}{\|\vec{a}\|}$.

If two vectors \vec{a} and \vec{a}' are perpendicular, then any nonzero vector \vec{b} lying in the same plane as \vec{a} and \vec{a}' can be **resolved** into vectors parallel to \vec{a} and \vec{a}' with the formula

$$\vec{b} = \overrightarrow{\text{pr}_a b} + \overrightarrow{\text{pr}_{a'} b}$$

Example C. Given $\vec{a} = 4\vec{i} + 2\vec{j}$, $\vec{a}' = \vec{i} - 2\vec{j}$, and $\vec{b} = \vec{i} + 3\vec{j}$, resolve \vec{b} into vectors parallel to \vec{a} and \vec{a}' .

See the text for an explanation and Example 7 involving work done by a constant force \mathbf{F} on an object moving along a line from P to Q . The solution depends upon resolving \mathbf{F} into a vector parallel to \overrightarrow{PQ} .