## MATH 431-2018 PROBLEM SET 3

DUE THURSDAY 20 SEPTEMBER 2018

- (1) (Midpoints)
  - (a) Let p, q be points in Euclidean space  $\mathbb{E}^n$ . The midpoint  $\operatorname{mid}(p,q)$  of a line segment  $\overline{pq}$  (in Euclidean geometry) is defined as the unique point  $r \in \overrightarrow{pq}$  such that d(p,r) = d(q,r). Define  $\operatorname{mid}(p,q) \ \overline{pq}$  in affine geometry: that is, just in terms of translations, parallelism, etc. but not involving distance.
  - (b) In terms of affine coordinates (where p, q are represented by vectors in  $\mathbb{R}^n$ ), find a formula for  $\mathsf{mid}(p, q)$ .
- (2) (Affine combinations)

Vectors in a vector space can be added. How can we do this in an affine space?

If  $p_0, p_1, \ldots, p_k \in \mathbb{A}^n$  are k + 1 points in affine space, and  $t_0, t_1, \ldots, t_k \in \mathbb{R}$  scalars such that

(1) 
$$t_0 + t_1 + \dots t_k = 1,$$

we define an *affine combination*  $\sum_{i=0}^{n} t_i p_i$  as follows.

Choose a point  $O \in \mathbb{A}^n$  to be used as the *origin* and for each  $j = 0, \ldots, k$ , let  $\tau_j$  be the translation taking  $p_j$  to O. Then  $\tau_j(p_i)$  is a vector in  $\mathbb{R}^n$  (and when i = j, the zero vector **0**). Thus it makes sense to form the linear combination (a vector)

$$\sum_{i=0}^{k} t_i \tau_j(p_i) \in \mathbb{R}^n$$

and then translate O by this vector (apply the translation  $(\tau_j)^{-1}$ ) to obtain a point which we denote

$$^{(j)}\sum_{i=0}^{k}t_{i}p_{i} \in \mathbb{A}^{n}.$$

- (a) Show that  ${}^{(j)}\sum_{i=0}^{k} t_i p_i$  is independent of j, so we denote this just by  $\sum_{i=0}^{k} t_i p_i$ .
- (b) Show that if g is an affine transformation, then

$$g\left(\sum_{i=0}^{k} t_i p_i\right) = \sum_{i=0}^{k} t_i g(p_i).$$

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- (c) Does this characterize affine maps?
- (d) An alternative approach is to use the *linearization* of affine spaces as follows. Represent  $\mathbb{A}^n$  as the hyperplane  $\mathbb{R}^n \times \{1\}$ in the Cartesian product  $\mathbb{A}^n \times \mathbb{R}$ . (More accurately,  $\mathbb{A}^n$ identifies with  $\mathbb{R}^n \oplus \{1\}$  in the *direct sum*  $\mathbb{R}^n \oplus \mathbb{R} \cong \mathbb{R}^{n+1}$ . Then an affine map  $g = [A \mid \mathbf{b}]$  (that is, with linear part  $A \in \mathsf{Mat}_n(\mathbb{R})$  and translational part  $\mathbf{b} \in \mathbb{R}^n$ ) is represented by the (n + 1)-square matrix

$$\begin{bmatrix} A & \mathbf{b} \\ 0 \dots 0 & 1 \end{bmatrix}.$$

which preserves the hyperplane  $\mathbb{A}^n$  with last (n + 1-th) coordinate equal to 1.

(e) If  $p_0, \ldots, p_k$  respectively correspond to vectors  $\mathbf{p}_0, \ldots, \mathbf{p}_k \in \mathbb{R}^n \times \{1\}$  in this hyperplane, that is:

$$\mathbf{p} = \begin{bmatrix} p \\ 1 \end{bmatrix},$$

then the usual linear combination  $\sum_{i=0}^{k} t_i \mathbf{p}_i$  of vectors corresponds to the point  $\sum_{i=0}^{k} t_i p_i$ .

- (f) Explain why condition (1) is necessary.
- (3) Using the affine patch

$$\mathbb{A}^2 \hookrightarrow \mathbb{P}^2 (x, y) \longmapsto [x : y : 1]$$

which of the following sets of homogeneous coordinates represent the point  $(0.2, -0.5) \in \mathbb{A}^2$ ?

- (a) [0.2:-0.5:0](b) [2:-5:1](c) [-4:10:2](d) [5:2:1](e) [-0.2:0.5:-1]Which of the following
- (4) Which of the following triples of homogeneous coordinates define a set of three collinear points in  $\mathbb{P}^2$ ? For those ones, find the homogeneous coordinates for the line containing them.

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(5) Here are four affine patches:

$$\mathbb{A}^{2} \xrightarrow{\mathcal{A}_{1}} \mathbb{P}^{2}$$

$$(y, z) \longmapsto [1:y:z]$$

$$\mathbb{A}^{2} \xrightarrow{\mathcal{A}_{2}} \mathbb{P}^{2}$$

$$(x, z) \longmapsto [x:1:z]$$

$$\mathbb{A}^{2} \xrightarrow{\mathcal{A}_{3}} \mathbb{P}^{2}$$

$$(x, y) \longmapsto [x:y:1]$$

$$\mathbb{A}^{2} \xrightarrow{\mathcal{A}_{4}} \mathbb{P}^{2}$$

$$(u, v) \longmapsto [u+1:u-v:u+v]$$

- (a) Find an ideal point for each of these affine patches.
- (b) Find the affine coordinates of the point [1:2:3] in terms of these three affine patches. That is, compute  $\mathcal{A}_i^{-1}([1:2:3])$  for i = 1, 2, 3, 4.
- (c) Let P be the parabola

$$\{(x,y) \in \mathbb{A}^2 \mid y = x^2\}$$

and consider the closure C of  $\mathcal{A}_3(P) \subset \mathbb{P}^2$ . Express C in homogeneous coordinates.

- (d) Does P have an ideal point?
- (e) Determine  $(\mathcal{A}_i)^{-1}(C)$  for i = 2, 3, 4 and their ideal points (if any).